

NAG Toolbox for MATLAB

d06ab

1 Purpose

d06ab generates a triangular mesh of a closed polygonal region in $\mathbb{R}^2$, given a mesh of its boundary. It uses a Delaunay–Voronoi process, based on an incremental method.

2 Syntax

```
[nv, nelt, coor, conn, ifail] = d06ab(nvb, edge, coor, weight, npropa,
itrace, 'nvint', nvint, 'nvmax', nvmax, 'nedge', nedge)
```

3 Description

d06ab generates the set of interior vertices using a Delaunay–Voronoi process, based on an incremental method. It allows you to specify a number of fixed interior mesh vertices together with weights which allow concentration of the mesh in their neighbourhood. For more details about the triangulation method, consult the D06 Chapter Introduction as well as George and Borouchaki 1998.

This function is derived from material in the MODULEF package from INRIA (Institut National de Recherche en Informatique et Automatique).

4 References

George P L and Borouchaki H 1998 *Delaunay Triangulation and Meshing: Application to Finite Elements* Editions HERMES, Paris

5 Parameters

5.1 Compulsory Input Parameters

1: **nvb** – int32 scalar

The number of vertices in the input boundary mesh.

Constraint: **nvb** ≥ 3 .

2: **edge(3,nedge)** – int32 array

The specification of the boundary edges. **edge(1,j)** and **edge(2,j)** contain the vertex numbers of the two end points of the j th boundary edge. **edge(3,j)** is a user-supplied tag for the j th boundary edge and is not used by d06ab.

Constraint: $1 \leq \mathbf{edge}(i,j) \leq \mathbf{nvb}$ and $\mathbf{edge}(1,j) \neq \mathbf{edge}(2,j)$, for $i = 1, 2$ and $j = 1, 2, \dots, \mathbf{nedge}$.

3: **coor(2,nvmax)** – double array

coor(1,i) contains the x co-ordinate of the i th input boundary mesh vertex, for $i = 1, \dots, \mathbf{nvb}$. **coor(1,i)** contains the x co-ordinate of the $(i - \mathbf{nvb})$ th fixed interior vertex, for $i = \mathbf{nvb} + 1, \dots, \mathbf{nvb} + \mathbf{nvint}$. For boundary and interior vertices, **coor(2,i)** contains the corresponding y co-ordinate, for $i = 1, \dots, \mathbf{nvb} + \mathbf{nvint}$.

4: **weight(*)** – double array

Note: the dimension of the array **weight** must be at least $\max(1, \mathbf{nvint})$.

The weight of fixed interior vertices. It is the diameter of triangles (length of the longer edge) created around each of the given interior vertices.

Constraint: $\mathbf{weight}(i) > 0.0$ if $\mathbf{nvint} > 0$, for $i = 1, 2, \dots, \mathbf{nvint}$.

5: **npropa** – int32 scalar

The propagation type and coefficient, the parameter **npropa** is used when the internal points are created. They are distributed in a geometric manner if **npropa** is positive and in an arithmetic manner if it is negative. For more details see Section 8.

Constraint: $\mathbf{npropa} \neq 0$.

6: **itrace** – int32 scalar

The level of trace information required from d06ab.

$\mathbf{itrace} \leq 0$

No output is generated.

$\mathbf{itrace} \geq 1$

Output from the meshing solver is printed on the current advisory message unit (see x04ab). This output contains details of the vertices and triangles generated by the process.

You are advised to set $\mathbf{itrace} = 0$, unless you are experienced with finite element meshes generation.

5.2 Optional Input Parameters

1: **nvint** – int32 scalar

Default: The dimension of the array **weight**.

The number of fixed interior mesh vertices to which a weight will be applied.

Constraint: $\mathbf{nvint} \geq 0$.

2: **nvmax** – int32 scalar

Default: The dimension of the array **coor**.

the maximum number of vertices in the mesh to be generated.

Constraint: $\mathbf{nvmax} \geq \mathbf{nvb} + \mathbf{nvint}$.

3: **nedge** – int32 scalar

Default: The dimension of the array **edge**.

the number of boundary edges in the input mesh.

Constraint: $\mathbf{nedge} \geq 1$.

5.3 Input Parameters Omitted from the MATLAB Interface

rwork, lrwork, iwork, liwork

5.4 Output Parameters

1: **nv** – int32 scalar

The total number of vertices in the output mesh (including both boundary and interior vertices). If $\mathbf{nvb} + \mathbf{nvint} = \mathbf{nvmax}$, no interior vertices will be generated and $\mathbf{nv} = \mathbf{nvmax}$.

2: **nelt – int32 scalar**

The number of triangular elements in the mesh.

3: **coor(2,nvmax) – double array**

coor(1, i) will contain the x co-ordinate of the $(i - \mathbf{nvb} - \mathbf{nvint})$ th generated interior mesh vertex, for $i = \mathbf{nvb} + \mathbf{nvint} + 1, \dots, \mathbf{nv}$; while **coor**(2, i) will contain the corresponding y co-ordinate. The remaining elements are unchanged.

4: **conn(3,2 × nvmax + 5) – int32 array**

The connectivity of the mesh between triangles and vertices. For each triangle j , **conn**(i, j) gives the indices of its three vertices (in anticlockwise order), for $i = 1, 2$ and 3 , and $j = 1, \dots, \mathbf{nelt}$.

5: **ifail – int32 scalar**

0 unless the function detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the function:

ifail = 1

On entry, **nvb** < 3,
 or **nvint** < 0,
 or **nvb** + **nvint** > **nvmax**,
 or **nedge** < 1,
 or **edge**(i, j) < 1 or **edge**(i, j) > **nvb**, for some $i = 1, 2$ and $j = 1, \dots, \mathbf{nedge}$,
 or **edge**(1, j) = **edge**(2, j), for some $j = 1, \dots, \mathbf{nedge}$,
 or **npropa** = 0;
 or if **nvint** > 0, **weight**(i) ≤ 0.0, for some $i = 1, \dots, \mathbf{nvint}$;
 or **lrwork** < 12 × **nvmax** + 15,
 or **liwork** < 6 × **nedge** + 32 × **nvmax** + 2 × **nvb** + 78.

ifail = 2

An error has occurred during the generation of the interior mesh. Check the definition of the boundary (arguments **coor** and **edge**) as well as the orientation of the boundary (especially in the case of a multiple connected component boundary). Setting **itrace** > 0 may provide more details.

7 Accuracy

Not applicable.

8 Further Comments

The position of the internal vertices is a function position of the vertices on the given boundary. A fine mesh on the boundary results in a fine mesh in the interior. To dilute the influence of the data on the interior of the domain, the value of **npropa** can be changed. The propagation coefficient is calculated as:

$\omega = 1 + \frac{a - 1.0}{20.0}$, where a is the absolute value of **npropa**. During the process vertices are generated on edges of the mesh $\mathcal{T}_i$ to obtain the mesh $\mathcal{T}_{i+1}$ in the general incremental method (consult the D06 Chapter Introduction or George and Borouchaki 1998). This generation uses the coefficient ω , and it is geometric if **npropa** > 0, and arithmetic otherwise. But increasing the value of a may lead to failure of the process, due to precision, especially in geometries with holes. So you are advised to manipulate the parameter **npropa** with care.

You are advised to take care to set the boundary inputs properly, especially for a boundary with multiply connected components. The orientation of the interior boundaries should be in **clockwise** order and

opposite to that of the exterior boundary. If the boundary has only one connected component, its orientation should be **anticlockwise**.

9 Example

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coor(1, 3) = 3.85317;  
coor(1, 4) = 3.67302;  
coor(1, 5) = 3.42705;  
coor(1, 6) = 3.12132;  
coor(1, 7) = 2.76336;  
coor(1, 8) = 2.36197;  
coor(1, 9) = 1.92705;  
coor(1, 10) = 1.4693;  
coor(1, 11) = 1;  
coor(1, 12) = 0.530697;  
coor(1, 13) = 0.072949;  
coor(1, 14) = -0.361971;  
coor(1, 15) = -0.763356;  
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coor(1, 34) = 2.36197;  
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coor(1, 48) = 0.029228;  
coor(1, 49) = 0.03806;  
coor(1, 50) = 0.048005;  
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coor(1, 53) = 0.084265000000000001;  
coor(1, 54) = 0.098396;  
coor(1, 55) = 0.113495;  
coor(1, 56) = 0.129524;  
coor(1, 57) = 0.146447;  
coor(1, 58) = 0.164221;  
coor(1, 59) = 0.182803;  
coor(1, 60) = 0.20215;  
coor(1, 61) = 0.222215;  
coor(1, 62) = 0.242949;  
coor(1, 63) = 0.264302;  
coor(1, 64) = 0.286222;  
coor(1, 65) = 0.308658;  
coor(1, 66) = 0.331555;  
coor(1, 67) = 0.354858;  
coor(1, 68) = 0.37851;  
coor(1, 69) = 0.402455;  
coor(1, 70) = 0.426635;  
coor(1, 71) = 0.450991;  
coor(1, 72) = 0.475466;  
coor(1, 73) = 0.5;  
coor(1, 74) = 0.5245339999999999;  
coor(1, 75) = 0.549009;  
coor(1, 76) = 0.573365;  
coor(1, 77) = 0.597545;  
coor(1, 78) = 0.62149;  
coor(1, 79) = 0.645142;  
coor(1, 80) = 0.668445;  
coor(1, 81) = 0.691342;  
coor(1, 82) = 0.713778;  
coor(1, 83) = 0.735698;  
coor(1, 84) = 0.757051;  
coor(1, 85) = 0.7777849999999999;  
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coor(1, 87) = 0.817197;  
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coor(1, 92) = 0.901604;  
coor(1, 93) = 0.915735;  
coor(1, 94) = 0.928864;  
coor(1, 95) = 0.940961;  
coor(1, 96) = 0.951995;  
coor(1, 97) = 0.96194;  
coor(1, 98) = 0.970772;
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coor(1, 102) = 0.994588;  
coor(1, 103) = 0.997592;  
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coor(1, 139) = 0.450991;  
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coor(1, 141) = 0.402455;  
coor(1, 142) = 0.37851;  
coor(1, 143) = 0.354858;  
coor(1, 144) = 0.331555;  
coor(1, 145) = 0.308658;  
coor(1, 146) = 0.286222;  
coor(1, 147) = 0.264302;  
coor(1, 148) = 0.242949;  
coor(1, 149) = 0.222215;  
coor(1, 150) = 0.20215;  
coor(1, 151) = 0.182803;  
coor(1, 152) = 0.164221;  
coor(1, 153) = 0.146447;  
coor(1, 154) = 0.129524;  
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coor(1, 308) = 2.11170731707317;
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coor(2, 10) = 2.96307;  
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coor(2, 89) = 0.026554;  
coor(2, 90) = 0.023817;  
coor(2, 91) = 0.021153;  
coor(2, 92) = 0.01858;  
coor(2, 93) = 0.016113;  
coor(2, 94) = 0.013769;  
coor(2, 95) = 0.011562;  
coor(2, 96) = 0.009507999999999999;  
coor(2, 97) = 0.007622;  
coor(2, 98) = 0.005915;  
coor(2, 99) = 0.004401;  
coor(2, 100) = 0.003092;  
coor(2, 101) = 0.002001;  
coor(2, 102) = 0.001137;  
coor(2, 103) = 0.00051;  
coor(2, 104) = 0.000128;  
coor(2, 106) = 3.5e-05;  
coor(2, 107) = 0.000137;  
coor(2, 108) = 0.000296;  
coor(2, 109) = 0.000497;  
coor(2, 110) = 0.000719;  
coor(2, 111) = 0.0009350000000000001;  
coor(2, 112) = 0.001112;  
coor(2, 113) = 0.001212;  
coor(2, 114) = 0.001197;  
coor(2, 115) = 0.001033;
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coor(2, 259) = -0.143552;  
coor(2, 260) = -0.142427;  
coor(2, 261) = -0.141266;  
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coor(2, 325) = -0.6500390243902439;
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coor(2, 328) = -0.6994292682926829;  
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coor(2, 334) = -0.798209756097561;  
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          0.01;  
          0.01;  
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          0.01;  
          0.01;  
          0.01;  
          0.01];  
npropa = int32(-5);  
itrace = int32(0);  
[nv, nelt, coorOut, conn, ifail] = d06ab(nvb, edge, coor, weight, npropa,  
itrace)  
  
nv =  
    2326  
nelt =  
    4358  
coorOut =  
    array elided  
conn =  
    array elided  
ifail =  
    0
```